

# AC Steady State Analysis → Chapter #8

- **Basic Characteristics of Sinusoidal Functions**
- **Phasor / Inverse Phasor Transformations & Diagrams**
- **Impedance and Admittance → R, L, C**
- **Equivalent Impedance / Equivalent Admittance**
- **Equivalent Circuit in Frequency Domain**
- **Apply Circuit Analysis Techniques to Frequency Domain Circuits**

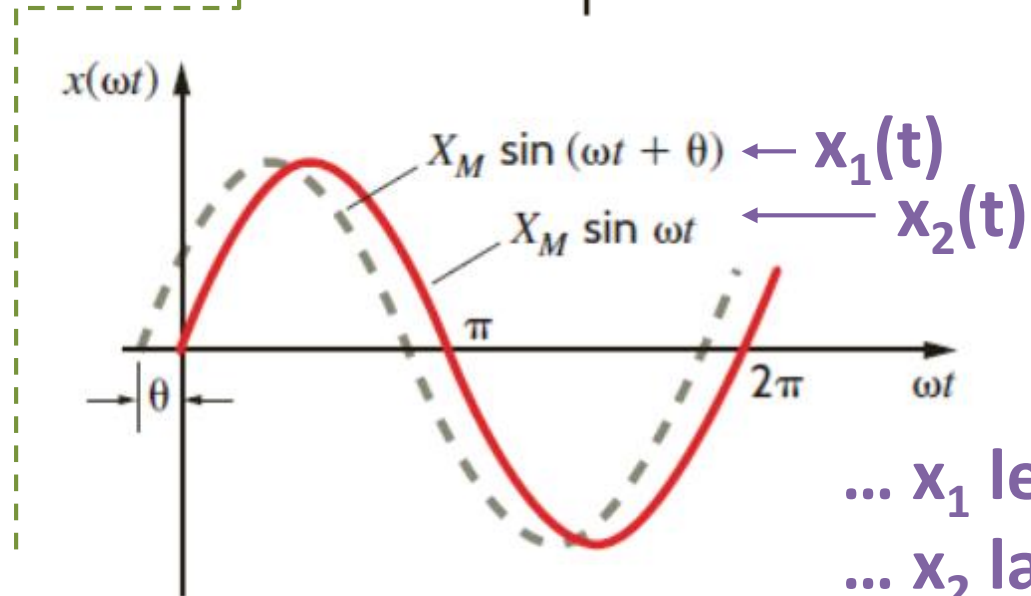
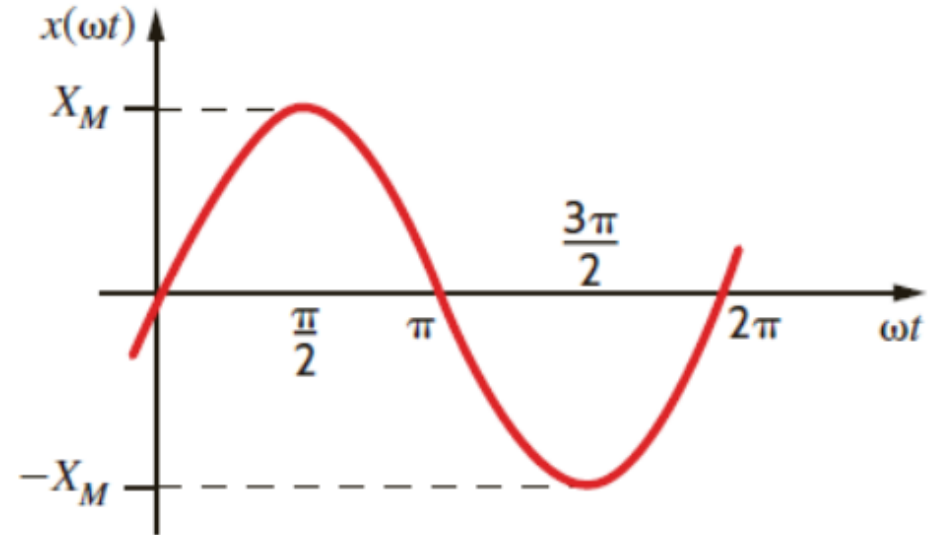
# Sinusoids

$$x(t) = X_M \cdot \sin(\omega t + \theta)$$

- $X_m$  → amplitude / maximum value
- $\omega$  → radian / angular frequency
- $\theta$  → phase angle

- $T$  → period
- $f = \frac{1}{T}$  → # cycles per second

$$\omega = \frac{2\pi}{T} = 2\pi f$$



...  $x_1$  leads  $x_2$  by  $\theta$

...  $x_2$  lags  $x_1$  by  $\theta$

# Trigonometric Identities

$$-\cos(\omega t) = \cos(\omega t \mp 180^\circ)$$

$$-\sin(\omega t) = \sin(\omega t \mp 180^\circ)$$

$$\cos(\omega t) = \sin\left(\omega t + \frac{\pi}{2}\right)$$

$$\sin(\omega t) = \cos\left(\omega t - \frac{\pi}{2}\right)$$

$$\sin(\alpha + \beta) = \sin(\alpha) \cos(\beta) + \cos(\alpha) \sin(\beta)$$

$$\cos(\alpha + \beta) = \cos(\alpha) \cos(\beta) - \sin(\alpha) \sin(\beta)$$

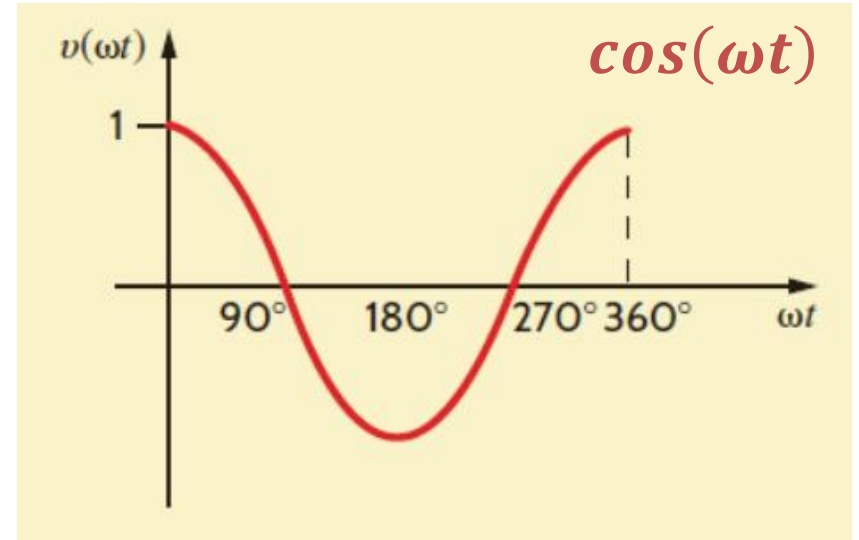
$$\sin(\alpha - \beta) = \sin(\alpha) \cos(\beta) - \cos(\alpha) \sin(\beta)$$

$$\cos(\alpha - \beta) = \cos(\alpha) \cos(\beta) + \sin(\alpha) \sin(\beta)$$

## Example 8.1

Plot the waveforms for the following functions:

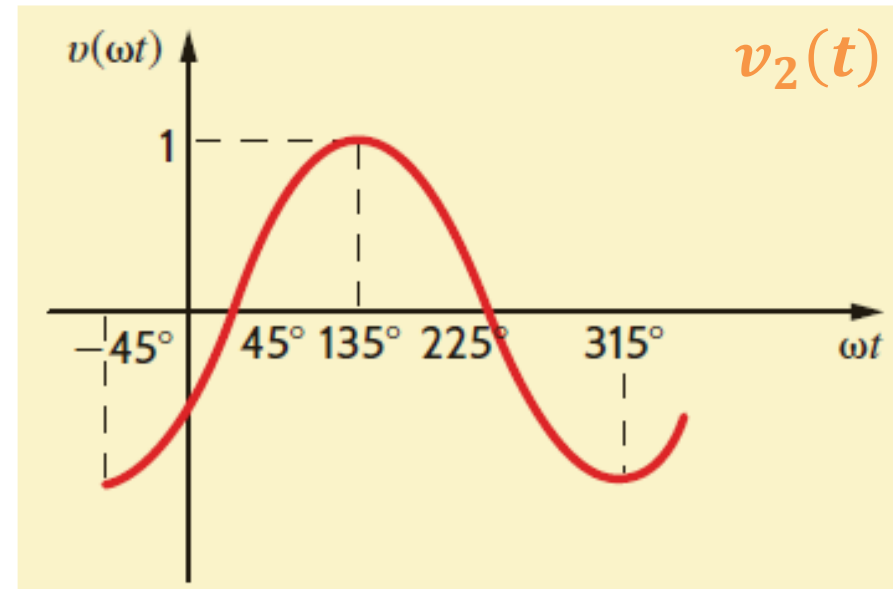
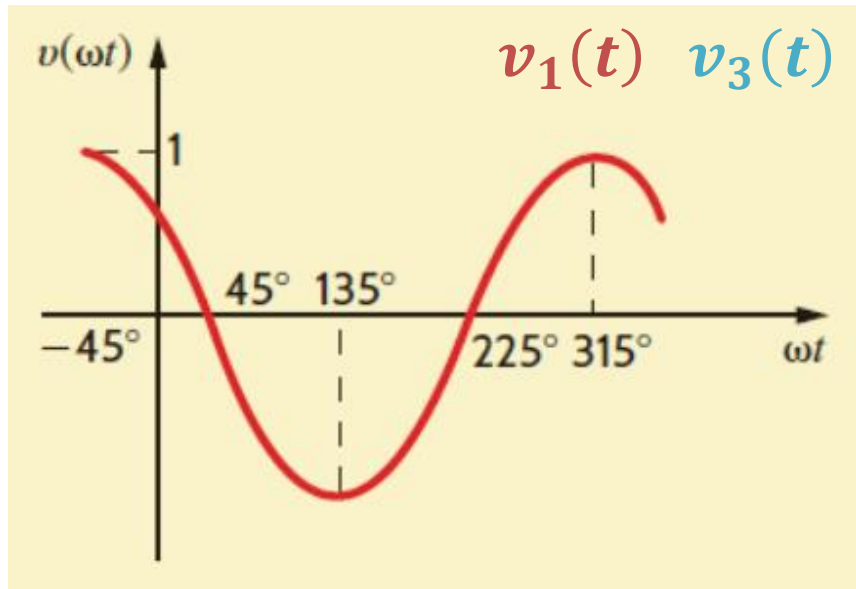
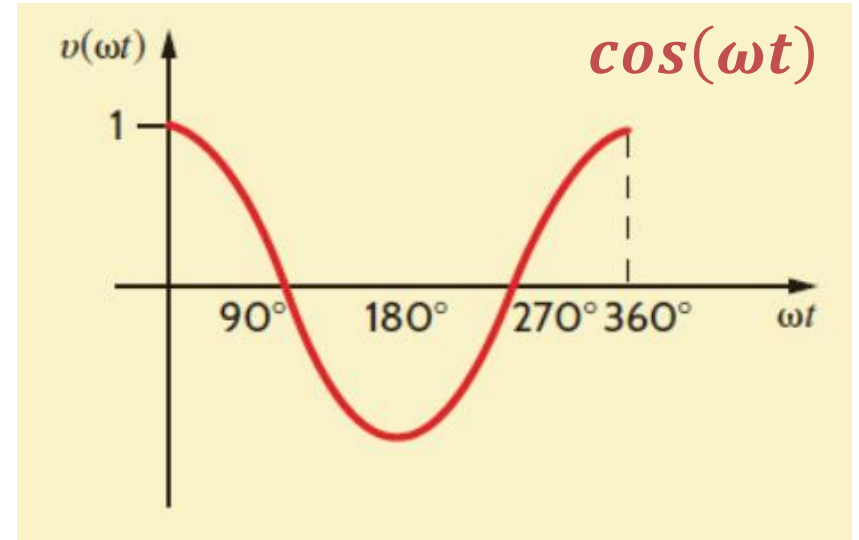
- $v_1(t) = \cos(\omega t + 45^\circ)$
- $v_2(t) = \cos(\omega t + 225^\circ)$
- $v_3(t) = \cos(\omega t - 315^\circ)$



## Example 8.1

Plot the waveforms for the following functions:

- $v_1(t) = \cos(\omega t + 45^\circ)$
- $v_2(t) = \cos(\omega t + 225^\circ)$
- $v_3(t) = \cos(\omega t - 315^\circ)$



## Example 8.2

**Determine the frequency and the phase angle between the two voltages:**

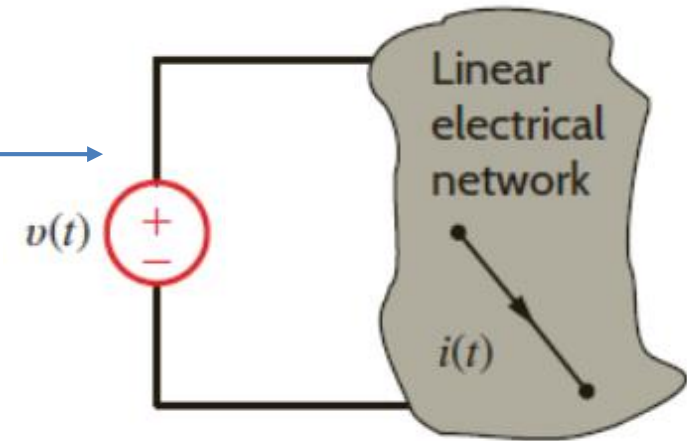
- $v_1(t) = 12 \sin(1000 \cdot t + 60^\circ) \text{ V}$  and
- $v_2(t) = -6 \cos(1000 \cdot t + 30^\circ) \text{ V}$

# Sinusoidal Forcing Functions

Constant Forcing Function  $\rightarrow$  Linear Network  
 $\therefore$  Constant Steady State Response



Sinusoidal Forcing Function  $\rightarrow$  Linear Network  
 $\therefore$  Sinusoidal Steady State Response

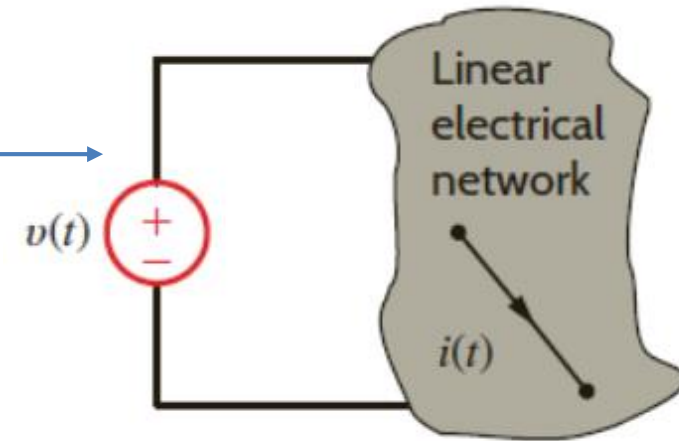


# Sinusoidal Forcing Functions

Constant Forcing Function → Linear Network  
 $\therefore$  Constant Steady State Response

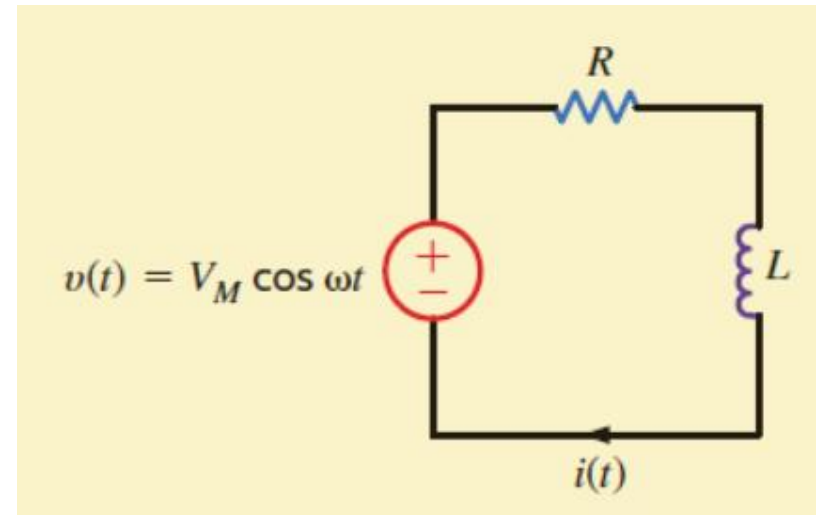


Sinusoidal Forcing Function → Linear Network  
 $\therefore$  Sinusoidal Steady State Response



## Example 8.3

Derive the expression for the current  $i(t)$ .



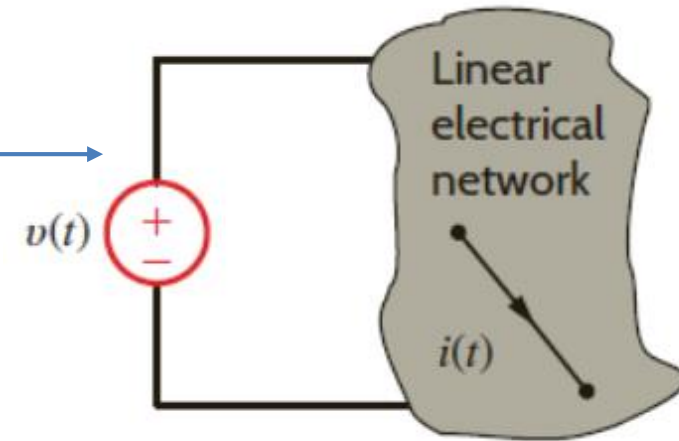


# Sinusoidal Forcing Functions

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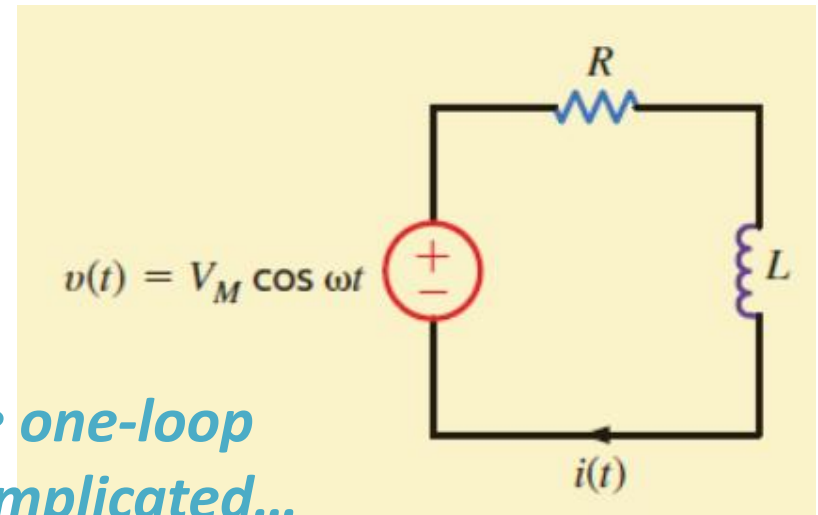
## Example 8.3

Derive the expression for the current  $i(t)$ .

$$v(t) = R \cdot i(t) + L \frac{di(t)}{dt}$$

where  $i(t) = I_M \cos(\omega t + \varphi)$

*Solution to the one-loop circuit is very complicated...*



# Sinusoidal Time Functions $\leftrightarrow$ Complex Numbers

This relationship leads to algebraic set of equations for currents and voltages in a network in which the coefficients of the variables are complex numbers.

## Euler's Equation

$$e^{j\omega t} = \underbrace{\cos(\omega t)}_{\substack{\text{Re}(e^{j\omega t}) \\ \text{real part}}} + \underbrace{j \sin(\omega t)}_{\substack{\text{Im}(e^{j\omega t}) \\ \text{imaginary part}}}$$

$j = \sqrt{-1}$

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$j = \sqrt{-1}$

## Forcing Function

$$v(t) = V_M e^{j\omega t}$$



$$v(t) = V_M \cos(\omega t) + jV_M \sin(\omega t)$$

As a consequence of linearity, the principle of superposition applies, hence ...

$$i(t) = I_M \cos(\omega t + \varphi) + jI_M \sin(\omega t + \varphi)$$



$$i(t) = I_M e^{j(\omega t + \varphi)}$$

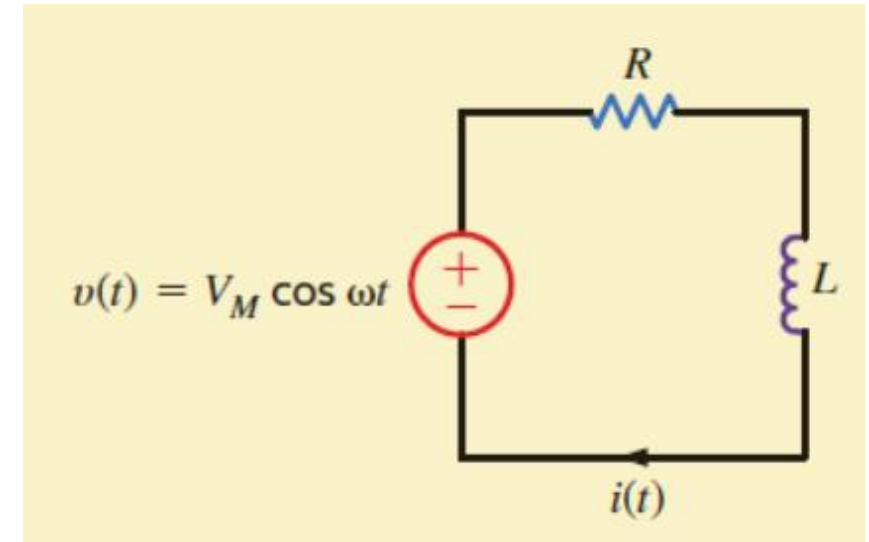
## Example 8.4

Derive the expression for the current  $i(t)$  using the forcing function  $v(t) = V_M e^{j\omega t}$  instead.

$$\text{KVL} \\ v(t) = R \cdot i(t) + L \frac{di(t)}{dt}$$

response

$$i(t) = I_M e^{j(\omega t + \varphi)}$$

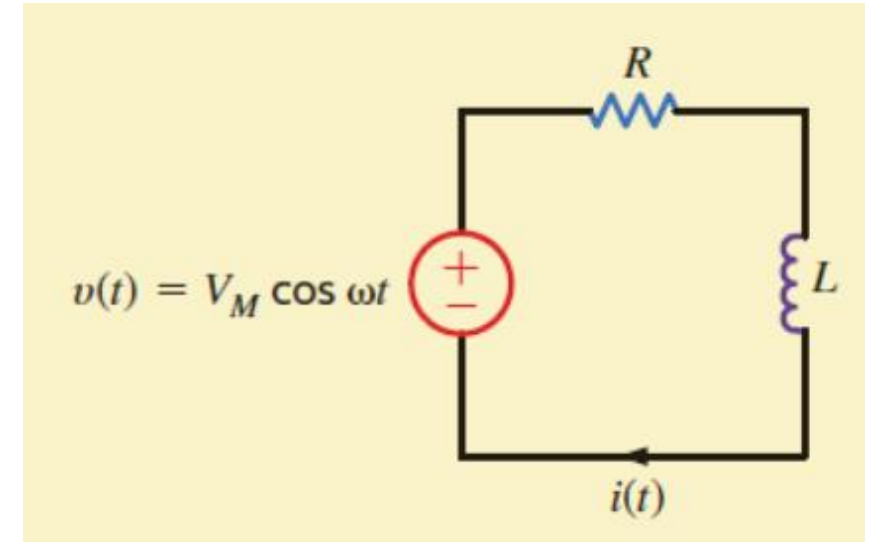


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Derive the expression for the current  $i(t)$  using the forcing function  $v(t) = V_M e^{j\omega t}$  instead.

$$\left. \begin{array}{l} \text{KVL} \\ v(t) = R \cdot i(t) + L \frac{di(t)}{dt} \\ \text{response} \\ i(t) = I_M e^{j(\omega t + \varphi)} \end{array} \right\} \text{Differential Equation}$$

$$V_M e^{j\omega t} = R I_M e^{j(\omega t + \varphi)} + L \frac{d}{dt} (I_M e^{j(\omega t + \varphi)})$$



### Solution

$$\therefore I_M = \frac{V_M}{\sqrt{R^2 + \omega^2 L^2}} \quad \therefore \varphi = -\tan^{-1} \left( \frac{\omega L}{R} \right)$$



$$i(t) = \frac{V_M}{\sqrt{R^2 + \omega^2 L^2}} \cos \left( \omega t - \tan^{-1} \left( \frac{\omega L}{R} \right) \right)$$

# Phasors

Representation of a complex number with just the magnitude and the phase angle.

- **Forcing Function**

$$v(t) = V_M e^{j(\omega t + \theta)} = V_M e^{j\omega t} e^{j\theta}$$

- **Steady State Response**

$$i(t) = I_M e^{j(\omega t + \varphi)} = I_M e^{j\omega t} e^{j\varphi}$$

$e^{j(\omega t)}$  → common to every term

# Phasors

Representation of a complex number with just the magnitude and the phase angle.

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- **Steady State Response**

$$i(t) = I_M e^{j(\omega t + \varphi)} = I_M e^{j\omega t} e^{j\varphi}$$

$e^{j(\omega t)}$  → common to every term

Assuming...

$$v(t) = V_M \cos(\omega t + \theta) = \text{Re}[V_M e^{j(\omega t + \theta)}]$$

$$i(t) = I_M \cos(\omega t + \varphi) = \text{Re}[I_M e^{j(\omega t + \varphi)}]$$

$$V = \text{Re}[V_M \langle \theta e^{j\omega t} \rangle] = V_M \langle \theta$$

$$I = \text{Re}[I_M \langle \varphi e^{j\omega t} \rangle] = I_M \langle \varphi$$

phasor

TABLE 8.1 Phasor representation

TIME DOMAIN	FREQUENCY DOMAIN
$A \cos(\omega t \pm \theta)$	$A \angle \pm \theta$
$A \sin(\omega t \pm \theta)$	$A \angle \pm \theta - 90^\circ$

# Learning Assessment

## E8.3 – Convert the following voltage functions to phasors

- $v_1(t) = 12 \cos(377t - 425^\circ) V$
- $v_2(t) = 18 \sin(2513t + 4.2^\circ) V$

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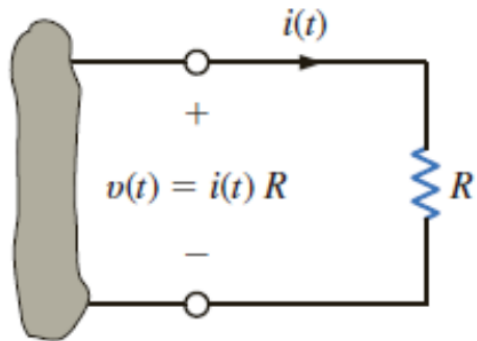
## E8.4 – Convert the following phasor to the time domain if the frequency is 400Hz.

- $V_3 = 10 \angle 20^\circ V$
  - $V_4 = 12 \angle -60^\circ V$
-



# Phasor Relationships → Resistor

- *Time Domain*

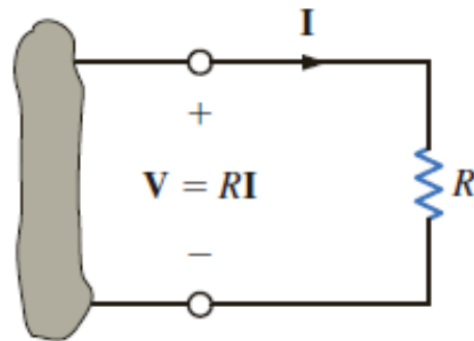


$$v(t) = R \cdot i(t)$$



$$V_M e^{j(\omega t + \theta_v)} = R \cdot I_M e^{j(\omega t + \theta_i)}$$

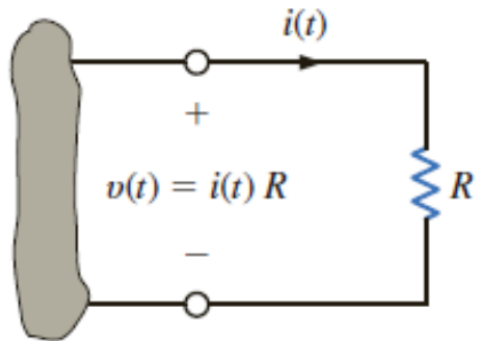
- *Frequency Domain*



- $v(t) = V_M e^{j(\omega t + \theta_v)}$
- $i(t) = I_M e^{j(\omega t + \theta_i)}$

# Phasor Relationships → Resistor

## • Time Domain

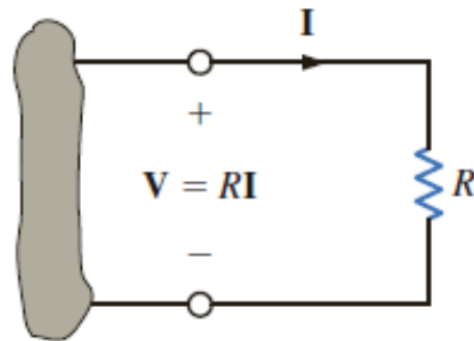


$$v(t) = R \cdot i(t)$$



$$V_M e^{j(\omega t + \theta_v)} = R \cdot I_M e^{j(\omega t + \theta_i)}$$

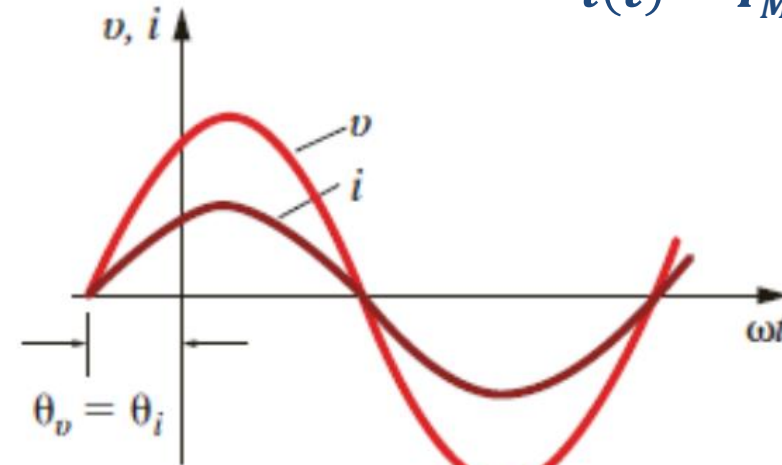
## • Frequency Domain



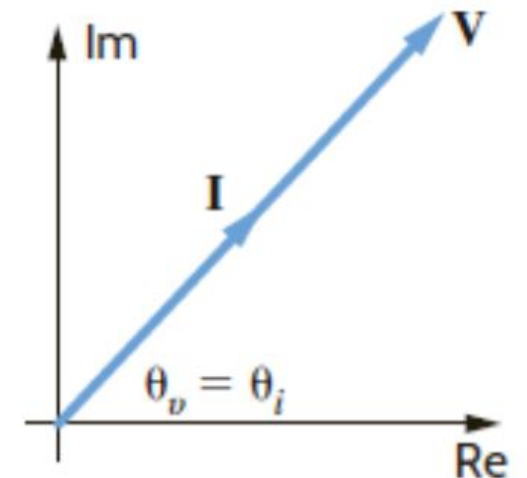
$$\therefore V_M e^{j\theta_v} = R \cdot I_M e^{j\theta_i}$$

$$\hookrightarrow V_M \angle \theta_v = R \cdot I_M \angle \theta_i$$

$$\therefore \theta_v = \theta_i \rightarrow v(t) \text{ and } i(t) \text{ are in phase}$$



- $v(t) = V_M e^{j(\omega t + \theta_v)}$
- $i(t) = I_M e^{j(\omega t + \theta_i)}$

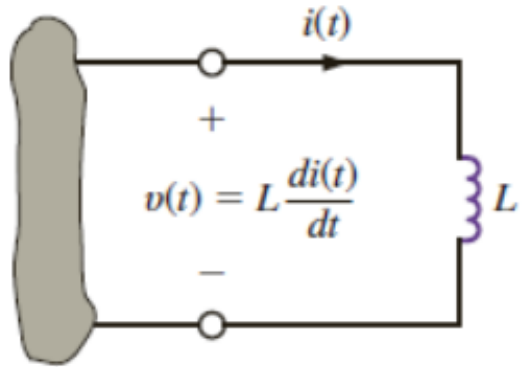


## Example 8.6

If the voltage  $v(t) = 24 \cos(377t + 75^\circ)$  V is applied to a 6- $\Omega$  resistor, find the resultant current.

# Phasor Relationships → Inductor

## • Time Domain

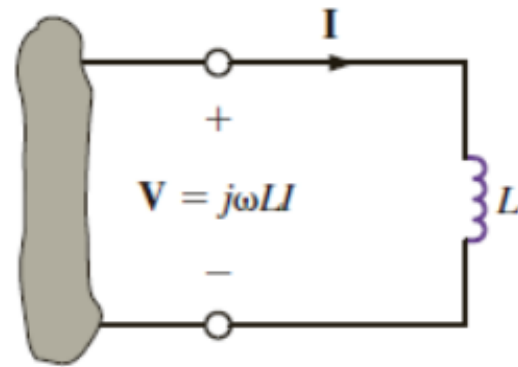


$$v(t) = L \cdot \frac{di(t)}{dt}$$



$$V_M e^{j(\omega t + \theta_v)} = L \cdot \frac{d}{dt} I_M e^{j(\omega t + \theta_i)}$$

## • Frequency Domain

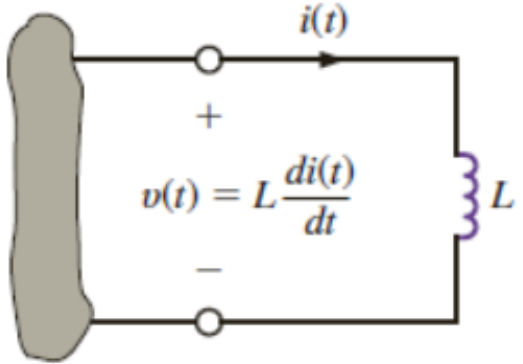


- $v(t) = V_M e^{j(\omega t + \theta_v)}$
- $i(t) = I_M e^{j(\omega t + \theta_i)}$

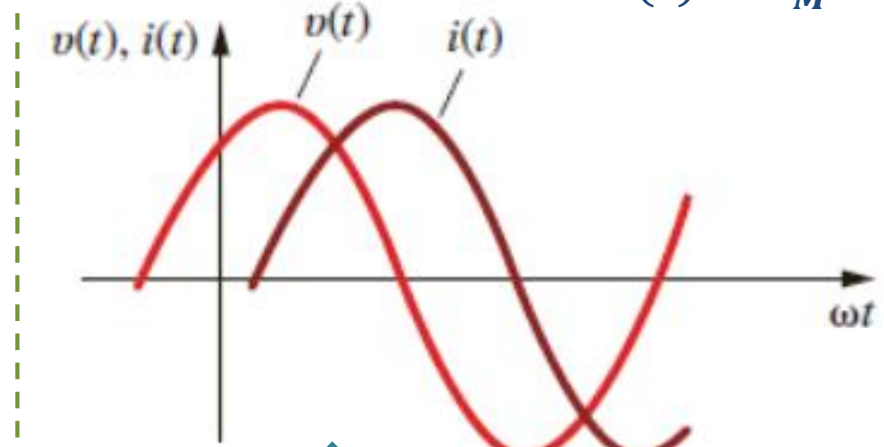
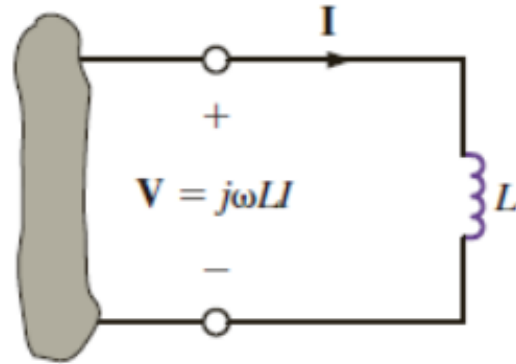
# Phasor Relationships → Inductor

- $v(t) = V_M e^{j(\omega t + \theta_v)}$
- $i(t) = I_M e^{j(\omega t + \theta_i)}$

## • Time Domain



## • Frequency Domain



$$v(t) = L \cdot \frac{di(t)}{dt}$$

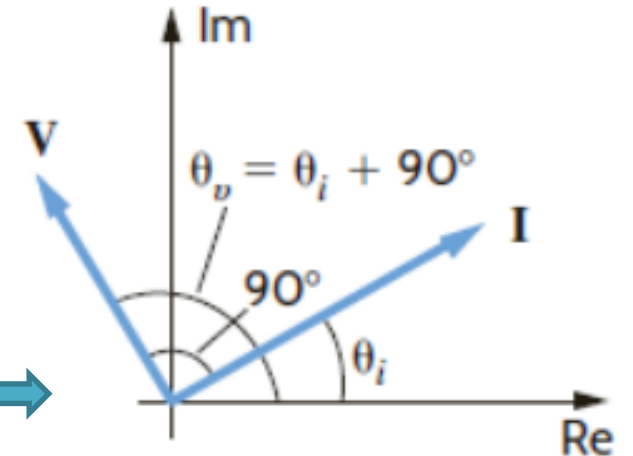


$$V_M e^{j(\omega t + \theta_v)} = L \cdot \frac{d}{dt} I_M e^{j(\omega t + \theta_i)}$$

$$\therefore V_M e^{j\theta_v} = j\omega L \cdot I_M e^{j\theta_i}$$

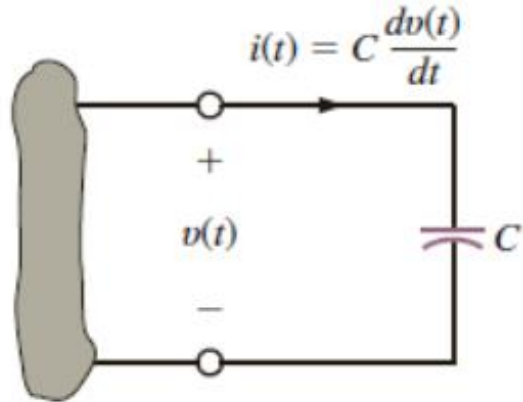
$$\hookrightarrow V_M \angle \theta_v = j\omega L \cdot I_M \angle \theta_i$$

$$\therefore \theta_v = \theta_i + 90^\circ \rightarrow v(t) \text{ lead } i(t) \text{ by } 90^\circ$$



# Phasor Relationships → Capacitance

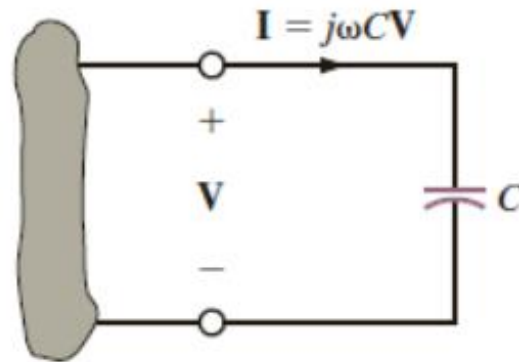
## • Time Domain



$$i(t) = C \cdot \frac{dv(t)}{dt}$$

$$I_M e^{j(\omega t + \theta_i)} = C \cdot \frac{d}{dt} V_M e^{j(\omega t + \theta_v)}$$

## • Frequency Domain

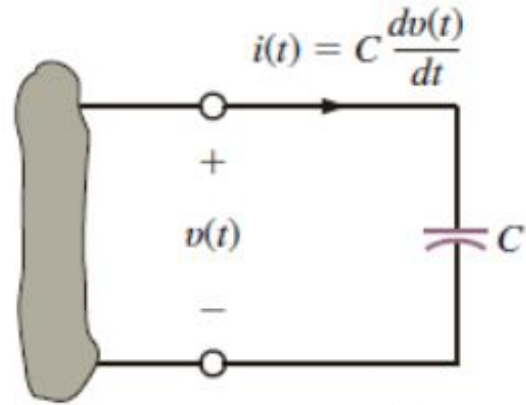


- $v(t) = V_M e^{j(\omega t + \theta_v)}$
- $i(t) = I_M e^{j(\omega t + \theta_i)}$

# Phasor Relationships → Capacitance

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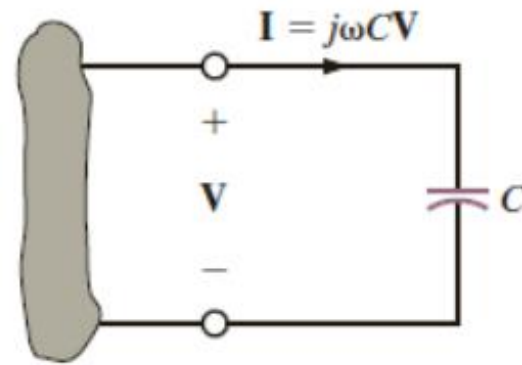
## • Time Domain



$$i(t) = C \cdot \frac{dv(t)}{dt}$$

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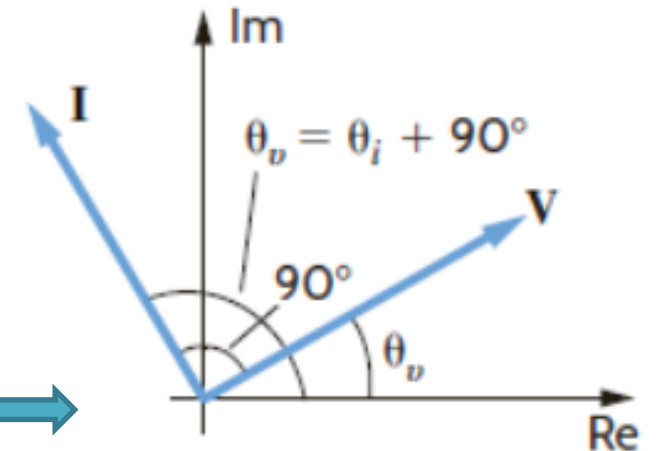
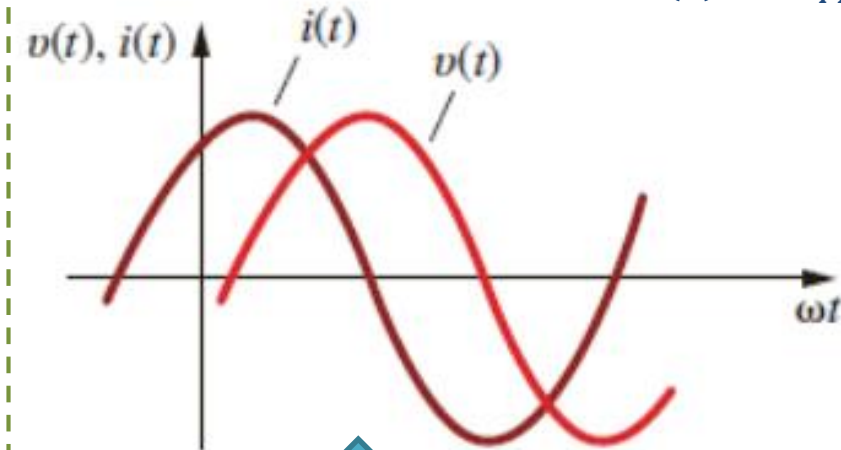
## • Frequency Domain



$$\therefore I_M e^{j\theta_i} = j\omega C \cdot V_M e^{j\theta_v}$$

$$\hookrightarrow I_M \angle \theta_i = j\omega C \cdot V_M \angle \theta_v$$

$$\therefore \theta_v = \theta_i - 90^\circ \rightarrow v(t) \text{ lags } i(t) \text{ by } 90^\circ$$



## Example 8.8

If the voltage  $v(t) = 100 \cos(314t + 15^\circ)$  V is applied to a 100- $\mu$ F capacitor, find the resultant current.