

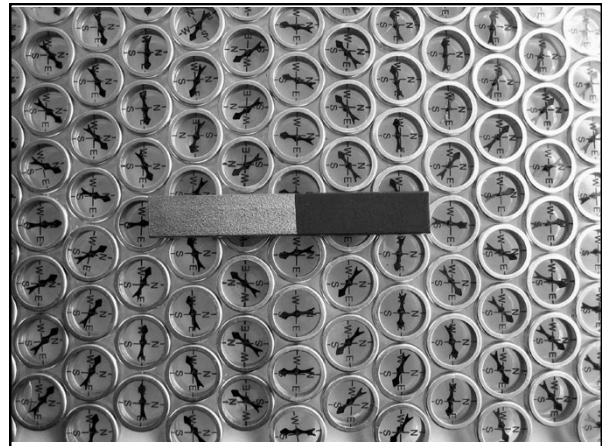


Magnetic Forces, Materials and Devices

INEL 4151 ch 8
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<http://www.treehugger.com/files/2008/10/spintronics-discover-could-lead-to-magnetic-batteries.php>



Section 8.2
MAGNETIC FORCE

Forces due to Magnetic fields

$B = \mu H$ = magnetic field density
 H = magnetic field intensity

Force can be due to:

- ① B on moving charge, Q
- ② B on current
- ③ Two currents

B is defined as force per unit current element

① Forces on a Charge

Analogous to the electric force: $\vec{F}_e = Q\vec{E}$

The total force is given by: $\vec{F} = \vec{F}_e + \vec{F}_m$

We have magnetic force: $\vec{F}_m = Q\vec{u} \times \vec{B}$

Note that F_m is perpendicular to both u and B

Stationary and Moving electron \uparrow

If the charge moving has a mass m , then:

$$\vec{F} = m \frac{d\vec{u}}{dt} = Q(\vec{E} + \vec{u} \times \vec{B})$$

Usually $F_m < F_e$

② Forces on a current element

The current element can be expressed as: $I d\vec{l} = \frac{dQ}{dt} d\vec{l} = dQ \frac{d\vec{l}}{dt} = dQ\vec{u}$

So we can write:

$$\vec{F}_m = Q\vec{u} \times \vec{B} = I\vec{l} \times \vec{B}$$

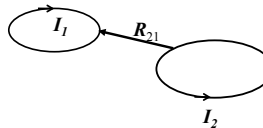
For closed path Line $I=[A]$ current element

$$\vec{F}_m = \oint_L I d\vec{l} \times \vec{B} \quad \vec{F}_m = \oint_S K d\vec{S} \times \vec{B} \quad \vec{F}_m = \int_V \vec{J} dv \times \vec{B}$$

For Surface $K=[A/m]$ current element For Volume $J=[A/m^2]$ current element

③ Force between two currents

- Each current produces a field B , which exerts a force on the other element. Let's find the Force on 1, due to the field produced by 2.

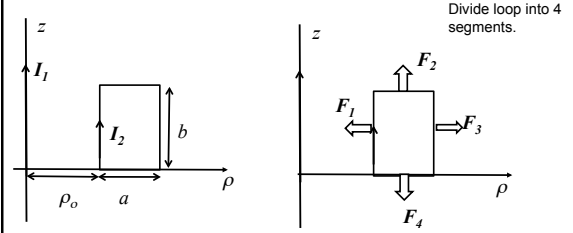


$$d\vec{F}_1 = I_1 d\vec{l}_1 \times \vec{B}_2$$

$$d\vec{B}_2 = \frac{\mu_0 I_2 d\vec{l}_2 \times \hat{a}_{R_{21}}}{4\pi R_{21}^2}$$

$$\vec{F}_1 = \frac{\mu_0 I_1 I_2}{4\pi} \oint_{L_1} \oint_{L_2} \frac{d\vec{l}_1 \times (d\vec{l}_2 \times \hat{a}_{R_{21}})}{R_{21}^2}$$

P.E. 8.4 Find the force experienced by the loop due to the field produced by the line,
if $I_1=10A, I_2=5A, \rho_o=20cm, a=1cm, b=30cm$

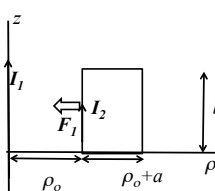


Divide loop into 4 segments.

Apply superposition $\vec{F}_1 = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4$

For segment #1, Force #1

Since I_1 is infinite long wire:



$$\vec{B}_1 = \frac{\mu_0 I_1 \hat{a}_\phi}{2\pi \rho_o}$$

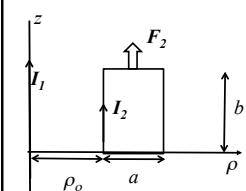
$$\vec{F}_1 = I_2 \int_{z=0}^b d\vec{l}_2 \times \vec{B}_1$$

$$\vec{F}_1 = I_2 \int_{z=0}^b dz \hat{a}_z \times \vec{B}_1$$

$$\vec{F}_1 = I_2 \frac{b \mu_0 I_1}{2\pi \rho_o} (-\hat{a}_\rho)$$

For segment #2,

The B field at segment #2 due to line current 1.



$$\vec{B}_1 = \frac{\mu_0 I_1 \hat{a}_\phi}{2\pi(\rho)}$$

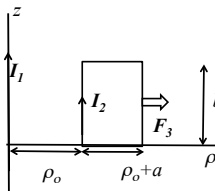
$$\vec{F}_2 = I_2 \int d\vec{l}_2 \times \vec{B}_1$$

$$\vec{F}_2 = I_2 \int_{\rho=\rho_o}^{\rho_o+a} d\rho \hat{a}_\rho \times \frac{\mu_0 I_1}{2\pi \rho} \hat{a}_\phi$$

$$\vec{F}_2 = \frac{\mu_0 I_1 I_2}{2\pi} \ln \frac{\rho_o + a}{\rho_o} (\hat{a}_z)$$

For segment #3, Force #3

The field at segment 3:



$$\vec{B}_1 = \frac{\mu_0 I_1 \hat{a}_\phi}{2\pi(\rho_o + a)}$$

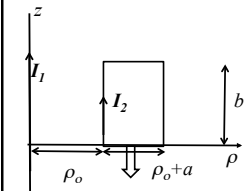
$$\vec{F}_3 = I_2 \int d\vec{l}_2 \times \vec{B}_1$$

$$\vec{F}_3 = I_2 \int_{z=b}^0 dz \hat{a}_z \times \frac{\mu_0 I_1}{2\pi(\rho_o + a)} \hat{a}_\phi$$

$$\vec{F}_3 = \frac{\mu_0 I_1 I_2 b}{2\pi(\rho_o + a)} (\hat{a}_\rho)$$

For segment #4,

The B field at segment #4 due to current 1.



$$\vec{B}_1 = \frac{\mu_0 I_1 \hat{a}_\phi}{2\pi \rho}$$

$$\vec{F}_4 = I_2 \int d\vec{l}_2 \times \vec{B}_1$$

$$\vec{F}_4 = I_2 \int_{\rho=\rho_o+a}^{\rho_o} d\rho \hat{a}_\rho \times \frac{\mu_0 I_1}{2\pi \rho} \hat{a}_\phi$$

$$\vec{F}_4 = -\frac{\mu_0 I_1 I_2}{2\pi} \ln \frac{\rho_o + a}{\rho_o} (\hat{a}_z)$$

The total force on the loop is

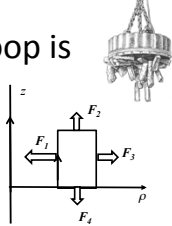
$I_1=10A, I_2=5A, \rho_o=20cm, a=1cm, b=30cm$

- The sum of all four:

$$\vec{F}_l = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4$$
- Note that 2 terms cancel out ($F_2 = -F_4$):

$$\vec{F}_{loop} = -I_2 \frac{b\mu_o I_1}{2\pi} \left[\frac{1}{\rho_o} - \frac{1}{(\rho_o + a)} \right] \hat{a}_\rho$$

They Attract!

$$\vec{F}_{loop} = -5 \frac{(0.3)\mu_o 10}{2\pi} \left[\frac{1}{0.2} - \frac{1}{(0.2+0.01)} \right] \hat{a}_\rho = -7.14 [\mu N] \hat{a}_\rho$$


Section 8.3-8.4

MAGNETIC TORQUE & MOMENT

Magnetic Torque and Moment

Inside a motor/generator we have many loops with currents, and the Magnetic fields from a magnet exert a torque on them.

The torque in [N m] is:

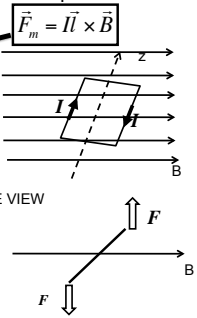
$$\vec{T} = \vec{r} \times \vec{F} = \vec{m} \times \vec{B}$$

Where m is the magnetic dipole moment:

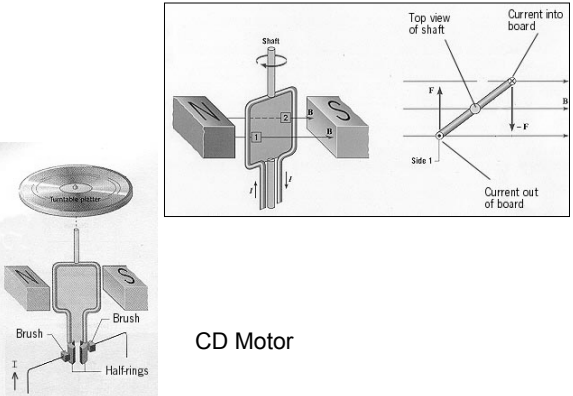
$$\vec{m} = IS \hat{a}_n$$

Where S is the area of the loop and \hat{a}_n is its unit normal. This applies if \mathbf{B} is uniform

$\vec{F}_m = I\vec{l} \times \vec{B}$



Torque on a Current Loop in a Magnetic Field



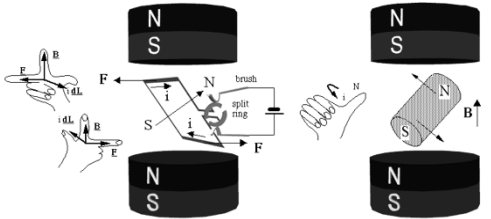
CD Motor

Magnetic Torque and Moment

The Magnetic torque can also be expressed as:

The torque in [N m] is:

$$\vec{T} = \vec{m} \times \vec{B}$$

$$= Q_m \vec{l} \times \vec{B} \quad \vec{m} = I(S)\hat{a}_n$$


Section 8.5, 8.6

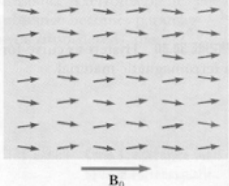
MAGNETIZATION

Magnetization

(similar to Polarization for E)

- Atoms have e- orbiting and spinning
 - Each have a magnetic dipole associated to it
- Most materials have **random orientation** of their magnetic dipoles if **NO external B-field** is applied.
- When a **B field is applied**, they **try to align** in the same direction.
- The **total magnetization** [A/m]

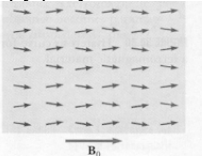
$$\vec{M} = \lim_{\Delta V \rightarrow 0} \frac{\sum_{k=1}^N \vec{m}_k}{\Delta V}$$



Magnetization

- The magnetization current density [A/m²]

$$\vec{J}_b = \nabla \times \vec{M}$$



- The total magnetic density is:

$$\vec{B} = \mu_o(\vec{H} + \vec{M})$$

- Magnetic susceptibility is:

$$\vec{M} = \chi_m \vec{H}$$

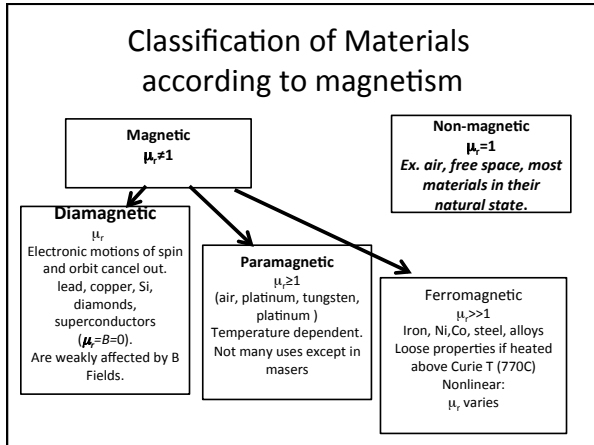
$$\vec{B} = \mu_o(1 + \chi_m)\vec{H}$$

$$\vec{B} = \mu_o \mu_r \vec{H}$$

- The relative permeability is:


$$\mu_r = (1 + \chi_m) = \frac{\mu}{\mu_o}$$

Permeability unit is [H/m].



$\chi_m = \mu_r - 1$ at 20°C

- Pure iron 150- 200,000
- Steel 50-100
- Iron oxide 720
- Iron Amonium alum 66
- Uranium 40
- Platinum 26
- Aluminum 2.2
- Magnesium 1.2
- Sodium 0.72
- Oxygen gas 0.19
- Amomia = -0.26



MagLev magnetic Levitation

- Use diamagnetic materials, which repel and are repelled by strong H fields.
- Superconductors are diamagnetic.
- Floating one magnet over another**
- Regular train 187 mph
- Maglev train 312 mph

<http://www.youtube.com/watch?v=alwbrZ4knpg>

P.E. 8.7 B-field in a magnetic material.

$$\vec{B} = 10e^{-y}\hat{z} \text{ mWb/m}^2$$

In a region with $\mu_r = 4.6$

- Find H , M and susceptibility

$$\chi_m + 1 = \mu_r$$

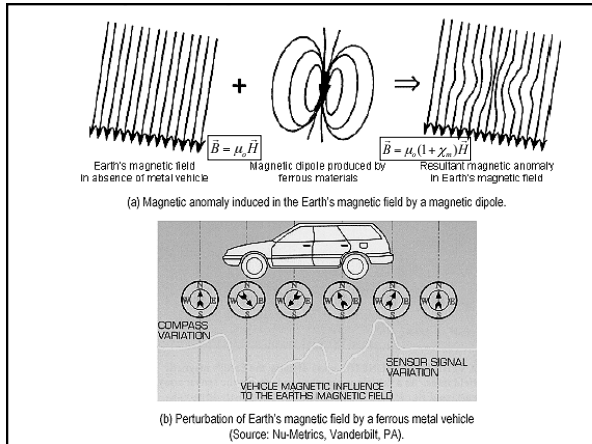
$$\chi_m = 3.6$$

$$H = \frac{\vec{B}}{\mu}$$

$$\vec{M} = \chi_m \vec{H}$$

$$\vec{H} = 1730e^{-y}\hat{z} [\text{A/m}]$$

$$\vec{M} = 6230e^{-y}\hat{z} \text{ A/m}$$



How to make traffic light go Green when driving a bike or motorcycle

- Stop directly on top of induction loop on the street
- Attach neodymium magnets to the vehicle
- Move on top of loop
- Push crossing button
- Video detectors

<http://www.wikihow.com/Trigger-Green-Traffic-Lights>
<http://www.labreform.org/education/loops.html>

B-H or Magnetization curve

- When an H-field is applied to ferromagnetic material, its B increases until saturation.

$$\mu = \frac{B}{H}$$

But when H is decreased, B doesn't follow the same curve.

Hysteresis Loop

Hysteresis Loop

- Some ferrites, have almost rectangular B-H curves, ideal for digital computers for storing information.
- The area of the loop gives the energy loss per volume during one cycle in the form of heat.
- Tall-narrow loops are desirable for electric generators, motors, transformers to minimize the hysteresis losses.

Section 8.7 (not covered)

MAGNETIC B.C.

Magnetic B.C. [Boundary Conditions]

- use Gauss Law & Ampere's Circuit law

$$\oint B \cdot dS = 0$$

$$\oint H \cdot dl = I$$

B.C.: Two magnetic media

- Consider the figure below:

$$\oint_S \vec{B} \cdot d\vec{S} = 0$$

$$B_{1n} \Delta S - B_{2n} \Delta S = 0$$

$$B_{1n} = B_{2n}$$

is continuous.

$$\mu_1 H_{1n} = \mu_2 H_{2n}$$

B.C.: Two magnetic media

- Consider the figure below:

$$\oint H \cdot dl = I = K \cdot \Delta w$$

$$= H_{1t} \Delta w + H_{1n} \frac{\Delta h}{2} + H_{2n} \frac{\Delta h}{2} - H_{2t} \Delta w - H_{2n} \frac{\Delta h}{2} - H_{1n} \frac{\Delta h}{2}$$

$$H_{1t} - H_{2t} = K$$

if no current at boundary
 $H_{1t} = H_{2t}$

Section 8.8

INDUCTORS AND INDUCTANCE

$$\Psi = \int_S \vec{B} \cdot d\vec{S} \text{ [Wb]}$$

Inductors

- So we can define the inductance as:

$$\lambda = LI$$
- If flux passes thru N turns, the total Flux Linkage is $\lambda = N\Psi$
- This is proportional to the current I

$$L = \frac{N\Psi}{I}$$
- The energy in Joules:

$$W_m = \frac{1}{2} LI^2$$

Units of Inductance

HENRY MILLIHENRY MICROHENRY

When more than 1 inductor

circuit 1 circuit 2

*Don't confuse the Magnetization vector, M, with the mutual inductance!



Self-inductance

$$L_1 = \frac{\lambda_{11}}{I_1} = \frac{N_1 \Psi_1}{I_1}$$

$$L_2 = \frac{\lambda_{22}}{I_2} = \frac{N_2 \Psi_2}{I_2}$$

- The total energy in the magnetic field is the sum of the energies:

$$W_m = W_1 + W_2 + W_{12}$$

$$= \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2 \pm M_{12} I_1 I_2$$
- The positive is taken if currents I_1 and I_2 flow such that the magnetic fields of the two circuits strengthen each other.

See table 8.3 in textbook with formulas for inductance of common elements like coaxial cable, two-wire line, etc.

P.E. 8.10 Solenoid

A long solenoid with 2 x 2 cm cross section has iron core (permeability is 1000x) and 4000 turns per meter. If carries current of 0.5A, Find:

- Self inductance per meter, L'

$$L' = \frac{L}{l} = N \Psi / I$$

$$\Psi = BS$$

$$B = \mu H = \frac{\mu N I}{l} = \mu n I$$

Central part of solenoid

Note L is independent of current

$$= 1000 \mu_0 (4000)^2 (2cm)^2$$

$$= 8.042 H / m$$

Section 8.10

MAGNETIC CIRCUITS

Magnetic Circuits

- Magnetomotive force
In units of ampere-turns

$$\mathcal{F} = NI = \int H \cdot dl$$
- Reluctance

$$\mathcal{R} = \frac{l}{\mu S}$$
- Like $V=IR$

$$\mathcal{F} = \Psi \mathcal{R}$$
- Ex: magnetic relays, motors, generators, transformers, toroids
- Table 8.4 presents analogy between magnetic and electric circuits

Magnetic Circuits

(a)

(b)

Figure 8.24 Analogy between (a) an electric circuit, and (b) a magnetic circuit.

Magnetic Circuits

Figure 3. Magnetic nucleus with air gap (a) and an equivalent magnetic circuit (b).

ELECTRIC CIRCUIT RULES APPLY!

(a) $I = \frac{V}{(R_1 + R_2)}$

(b) $\phi = \frac{F}{(R_1 + R_2)}$

$\mathcal{R} = \frac{l}{\mu S}$

$\mathcal{F} = \Psi \mathcal{R}$

$\Psi = \Psi_1 + \Psi_2$

Ex. Find current in coil needed to produced magnetic field density of 1.5T in air gap.
Assume $\mu_r=50$ and all cross sectional area is 10 cm²

$\mathcal{R}_1 = \frac{l}{\mu S} \quad \mathcal{R}_2 = \frac{0.30}{50\mu_o 10/10^4} = \mathcal{R}_3$

$\mathcal{R}_3 = \frac{0.09}{50\mu_o 10/10^4} \quad \mathcal{R}_{air} = \frac{0.01}{1\mu_o 10/10^4}$

$\mathcal{F} = NI = 400I = \Psi \mathcal{R}_T$

$\Psi = \Psi_a = B_a S$

$I = 44.16A$

8.42 A cobalt ring ($\mu_r=600$) has mean radius of 30cm.

- If a coil wound on the ring carries 12A, calculate the N required to establish an average magnetic flux density of 1.5 Teslas in the ring.

$\mathcal{F} = NI = \oint H \cdot dl$

$NI = Hl$

radius of 30cm

$$N = \frac{Bl}{\mu\mu_o I} = \frac{1.5 \times 2\pi(0.3)}{600\mu_o 12} = 313 \text{ vueltas}$$